Adiabatic Demagnetization Refrigerators (ADR)

Introduction from the application side

Jean-Marc Duval



cea





Lanef Demagnetization Day

Grenoble, 20 Septembre 2021



Adiabatic Demagnetization Refrigerators

1. Description and operation



2. Core components

- Magnetocaloric materials
- Heat switches
- Superconducting coils
- Electronics
- ...

3. Applications

- Laboratory work
- Space applications



Paixao et al, 2018

•SBT* Entropy, Temperature and Magnetic field

Magnetocaloric materials :

Temperature variations (or cooling /heating) with varying magnetic field



diagram S versus T (and not T versus S)

J. Tuoriniemi, A Casey and other presentations on nuclear demagnetization refrigerator

⁽Adiabatic) Nuclear Demagnetization Refrigerator



Examples of materials : alum and single crystal





"GGG" (Gadolinium Gallium Garnett) Single crystal and thermal bus

Crystal obtained by Czochralski method

GGG well adapted for 4K – 1 K cooling



Adiabatic Demagnetization Refrigerator



Heart of the system: magnetocaloric materials (typically paramagnetic)

Magnetic system (superconducting coil)

- Variation B => variation T

Heat switch + thermal interface







Adiabatic Demagnetization Refrigerator



Heart of the system: magnetocaloric materials (typically paramagnetic)

Magnetic system (superconducting coil)

- Variation B => variation T

Heat switch + thermal interface

Magnetic shielding (ferromagnetic)

 => Reduces perturbations on detectors

Mechanical support

- Thermal insulation (e.g. Kevlar)

Large temperature ratio

4 K to 100 mK (factor 40) achievable

Excellent efficiency

Limited by heat switch and support Only true at very low temperature <~10 K

Continuous operation with 2 stages

Multi-stage operation : continuous cooling

Parallel configuration

- Stages are operating in opposing phase
- Constant temperature on the cold interface



Advantage of continuous operation

Smaller stages (each can be sized for ~1 hour), no need to design for >10 hours operation

Parallel configuration is complex

4 Heat Switches required

Series configuration continuous cooling



See work of P. Shirron et al (NASA/Goddard) on continuous operation

BT Continuous operation with 2 stages

Series configuration brings key advantages :

- Only 2 heat switches
- Lower mass of stage 2 (smaller magnetic field)

In most cases, series configuration leads to a more optimized design

Continuous coolers design

mass and efficiency

Focus on optimization of



D. Schmoranzer presentation on continuous nuclear demagnetization refrigerator

Cold interface

Factor of merit / Objectives



Magnetocaloric material => Mass and Volume (Proportional to material and B)

Heat switches, Support => Thermal efficiency



ADR Coolers

1. Description and operation

2. Core components

- Magnetocaloric Materials
- Heat switches
- Superconducting coils
- Electronics
- ...

3. Applications

- Laboratory work
- Space applications







Paixao et al, 2018







Difficult to present a diagram => ST diagram are best!

Standard model based on free ion

approximation

$$Z = \left[\sum_{m=-l}^{l} P(E_m)\right]^{n.N_0}$$

$$S = k_b \frac{d}{dT} (T \ln Z)$$

$$\frac{S(B,T)}{R} = \ln\left[\frac{\sinh(2J+1)\frac{x}{2}}{\sinh\frac{x}{2}}\right] + \frac{x}{2} \coth\left(\frac{x}{2}\right) - \frac{(2J+1)}{2} x \coth\left((2J+1)\frac{x}{2}\right)$$
$$x = \frac{g\mu_B}{k_B} \frac{B}{T}$$



Boltzmann distribution

$$P(E_m) \propto e^{-\frac{mg\mu_B}{k_B}.B/T}$$

$$S_{\max} = nR\ln(2J+1)$$

$$\frac{S(B,T)}{R} = \ln\left[\frac{\sinh(2J+1)\frac{x}{2}}{\sinh\frac{x}{2}}\right] + \frac{x}{2}\coth\left(\frac{x}{2}\right) - \frac{(2J+1)}{2}x\coth\left((2J+1)\frac{x}{2}\right)$$



Constant B/T => Constant P(Em) => constant S => adiabatic cooling

Free ion model can't represent low field behavior

- Interactions at low field
- Impact on design and prediction

• Optimum material is a compromise

- Maximize Smax and hence J and ions density
- Minimize Bmax and hence g (Lande factor)
- Minimize magnetic moment interactions (for low temperature operations)

Optimum material for each use and temperature range

- Need the full S versus T diagram (magnetization or DS plots are usually insufficient)

More on materials : see M. Zhitomirsky and E. Riordan presentations

Coil and Magnetic shielding

Superconducting coil

- Generates a magnetic field of several T
- For space application, lowest current as possible (typically 2 amps)
- Manufacturing : vacuum impregnation or « wet winding »

G. Donnier-Valentin on superconducting coil

Magnetic shielding

- Necessary to protect sensitive detectors and materials
- Typical solution :
 - Ferromagnetic shield
 - For high field : active shielding (based on NMR design)
- Innovative solution based on superconducting shielding









Magnetic shielding



Illustration credit A. Leon, DSBT, 2020

B Finemet NO Fe-(3 wt %)Si Mumetal (Ni₈₀Fe₁₅Mo₅)

Choice of ferromagnetic materials depends on magnetic field

Characterization needed at low temperature!



Heat switches

Purpose : switching from thermally conductive to insulator

► 3 main technologies

- Mechanical heat switches

- Gas-gap heat switches

- Superconducting heat switches





Mechanical heat switches

Principle

- Mechanical contacts
- Activation by a motor

Characteristics



No (or low) OFF conduction



Limited ON conduction (mechanical contact)



Moving parts => risk of failure

Use

- Very efficient for long hold time experiment (no OFF conductance)
- Not suitable for continuous cooler (low ON conduction)
- Labs / Rocket/Balloon



Gas gap heat switches



- Sealed device filled with helium gas
- Activation (ON or OFF) controlled by temperature of adsorption pump
- Heat flows through two main copper parts and a gas gap

Copper parts Gap (≈ 100 μm) Miniature adsorption pump Weater Low conductivity wall (Ta6V, SS) Copper parts Scheme L. Duband



No moving parts, reliable, high ON/OFF ratio (>1000), good for T>0.3 K

Superconducting heat switches

Principle

- Low heat conductivity of superconducting material
- Transition from normal to SC thanks to applied magnetic field (~10s of mT)



Material candidates

Aluminum, Lead, Indium, ...

Critical points

Efficient only T<0.1 Tc Contact heat conductivity Magnetic system design Aluminum, Lead, Indium, ...

Only for T<<1.0 K

Main technology for T<0.2 K





S. Triqueneaux on nuclear adiabatic demagnetization

Key component : heat switches

>3 heat switches technologies

Mechanical heat switches

Mechanically connect two parts

- Excellent OFF position (~0)
- Low ON conductivity (contact resistance)



Hagmann et Richards, 1995

Excellent for one-shot ADR (except reliability) Not adapted for continuous ADR + Others (magnetoresistive ...)

Gas Gap Heat switches

Evacuate gas to pass OFF position

- Excellent ON position (T>0.5 K)
- Slow switching

Concentric shape



Superconducting heat switches « break » superconductivity with magnetic field



(Continuous ADR)

Heat switches are crucial for continuous operation (thermal efficiency depends 90% of heat switches and thermal links)

Other (also important) points

Temperature measurement

Superconducting coil current control

Commercial solutions : Lakeshore, AMI, ...

Specific developments at I. Neel (ex MMR3) and at DSBT and others

Quench protection

 Typical system based on diodes back to back in parallel with coil (dissipated energy in case of quench)

Current leads

- HTS superconducting wire commercially available for cryostat equipment
- Specific development needed for space

Algorithm for continuous design

Dedicated development for each experiments

Modelling and performance predictions





ADR Coolers

1. Description and operation

2. Core components

- Magnetocaloric Materials
- Heat switches
- Superconducting coils
- Electronics
- ...

3. Applications

- Laboratory work
- Space applications







First experimental demonstration

Attainment of Temperatures Below 1° Absolute by Demagnetization of $Gd_2(SO_4)_3 \cdot 8H_2O$

Predicted from the 1920s

- Giauque
- Debye

First demonstration in 1933

- Giauque, 1933

We have recently carried out some preliminary experiments on the adiabatic demagnetization of $Gd_2(SO_4)_3$ •8H₂O at the temperatures of liquid helium. As previously predicted by one of us, a large fractional lowering of the absolute temperature was obtained.

An iron-free solenoid producing a field of about 8000 gauss was used for all the measurements. The amount of $Gd_2(SO_4)_3 \cdot 8H_2O$ was 61 g. The observations were checked by many repetitions of the cooling. The temperatures were measured by means of the inductance of a coil surrounding the gadolinium sulfate. The coil was immersed in liquid helium and isolated from the gadolinium by means of an evacuated space. The thermometer was in excellent agreement with the temperature of liquid helium as indicated by its vapor pressure down to $1.5^{\circ}K$.

On March 19, starting at a temperature of about 3.4° K, the material cooled to 0.53° K. On April 8, starting at about 2°, a temperature of 0.34° K was reached. On April 9, starting at about 1.5°, a temperature of 0.25° K was attained.

It is apparent that it will be possible to obtain much lower temperatures, especially when successive demagnetizations are utilized.

> W. F. GIAUQUE D. P. MACDOUGALL

Department of Chemistry, University of California, Berkeley, California, April 12, 1933.

Giauque, W. F., et D. P. MacDougall. « Attainment of Temperatures Below 1° Absolute by Demagnetization of Gd2(SO4)3·8H2O ». Physical Review 43, nº 9 (1 mai 1933): 768-768.

Applications and current status

- Main technology until the 1960's for low temperature physics
- Mostly replaced by dilution fridge : more powerful, continuous cooling
- Renewed interest for space application (including rockets or balloons) since the 1990s
- Takes advantages of availability of superconducting coils

Laboratory applications

Mostly in competition with dilution for ground application

 Limited in energy (cooling power and experiment time) and mostly replaced by dilution

Advantages

- Easy control of temperature
- Lower cost (than dilution coolers)
- Reliability
- No ³He needed

Application for specific needs

- Commercial coolers (Entropy, HPD, ...)
- PPMS
 - Takes advantage of existing magnetic system

C. Marcenat presentation on PPMS

- Laboratory demonstration of continuous cooling
- Considered for high cooling power application
 - LHC studies in the 1980-90s
 - Looked again for e.g. FCC study



P. Camus presentation on Easycool



4 "Subkelvin" missions launched, 1 ADR



4 missions, 3 cryocoolers technologies: Sorption, Dilution, ADR

References : Matsubara (1996), Ade et al, A&A(2011), Kelley (2016), "Status Report on Astro-H."



3 astrophysics missions in preparation





3-stage ADR for LiteBIRD

Interfaces:

- Low power dissipation on 2 K stage (<2 mW) and 4 K stage (<1 mW)
- High cooling at intermediate stage 45 $\mu W~$ ~350 mK
- Continuous (or high duty cycle) 100 mK cooling (2 μW)
- Take advantage of "new" material for a light 2K – 350 mK stage (YbGG)

Material manufacturing work done with Pheliqs (C. Marin)

See E. Riordan presentation on detailed properties of YbGG







Conclusion

► ADR technology developments mostly pushed by space applications

- Major technology for sub-kelvin cooling for space
- Useful technology for specific laboratory experiments

Technological developments in various fields

- Cryogenics and Space cryogenics
- Physics and theory
- Material science engineering
- Electronics
- Magnetism
- Mechanical and thermal engineering

Many communalities with nuclear demagnetization



I'm looking forward to hearing all your talks today...

and to working together in the future